

Learning

- **Learning process:**
 - Learner (a computer program) processes data D representing the past experiences and tries to either derive something reasonable about the data seen or to develop some appropriate response to future data
- **Example:**
 - Learner sees a set of patient cases with corresponding disease labels and tries to predict the disease for future patient cases

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Types of learning

Three main types:

- **Supervised learning**
 - Learning mapping between inputs x and desired outputs y
 - Teacher gives me y 's for the learning purposes
- **Unsupervised learning**
 - Learning relations between data components
- **Reinforcement learning**
 - Learning mapping between inputs x and desired outputs y
 - Critic does not give me y 's but instead a signal (reinforcement) of how good my answer was

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Supervised learning

Data: $D = \{d_1, d_2, \dots, d_n\}$ a set of n examples

$$d_i = \langle \mathbf{x}_i, y_i \rangle$$

\mathbf{x}_i is input vector, and y is desired output (given by a teacher)

Objective: learn the mapping $f : X \rightarrow Y$

$$\text{s.t. } y_i \approx f(x_i) \text{ for all } i = 1, \dots, n$$

Two types of problems:

- **Regression:** Y is **continuous**
Example: earnings, product orders \rightarrow company stock price
- **Classification:** Y is **discrete**
Example: temperature, heart rate \rightarrow disease

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Unsupervised learning

- **Data:** $D = \{d_1, d_2, \dots, d_n\}$

$$d_i = \mathbf{x}_i \text{ vector of values}$$

No target value (output) y to learn

- **Objective:**
 - learn relations between samples, components of samples

Types of problems:

- **Clustering**
Group together “similar” sample instances, e.g. patient cases
- **Density estimation**
 - Model probabilistically the population of samples

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Unsupervised learning. Density estimation

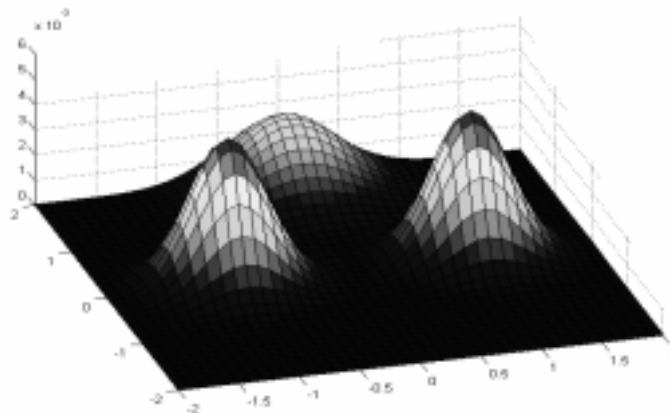
- We want to build the probability model of a population from which we draw samples $d_i = \mathbf{x}_i$



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Unsupervised learning. Density estimation

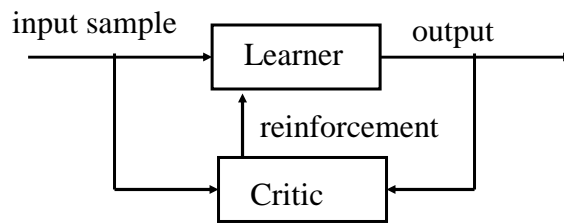
- Mixture of Gaussians – gives a probability distribution of a point in two dimensional space being seen)



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Reinforcement learning

- We want to learn: $f : X \rightarrow Y$
- We see samples of \mathbf{x} but not y
- Instead of y we get a feedback (reinforcement) from a **critic** about how good our output was

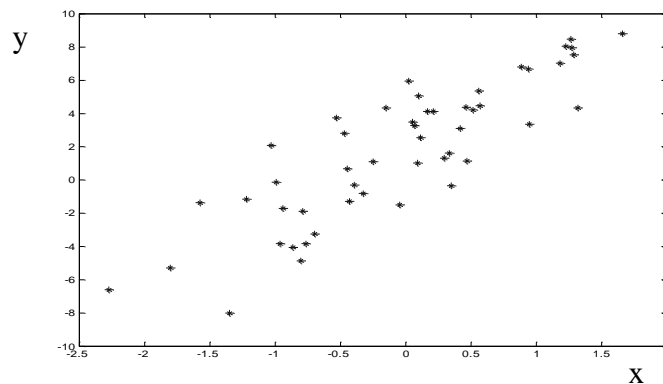


- The goal is to select output that leads to the best reinforcement

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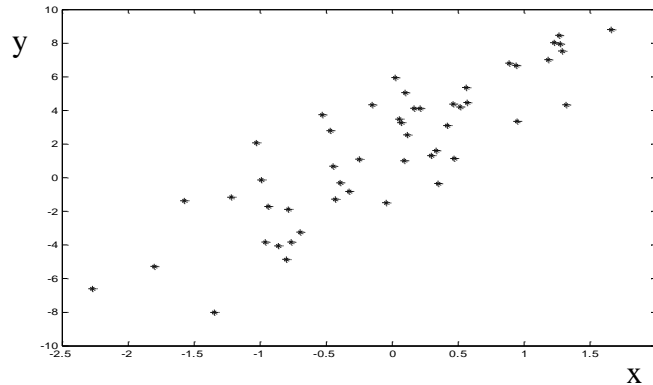
- Assume we see examples of pairs (\mathbf{x}, y) and want to learn the mapping $f : X \rightarrow Y$ for all possible values of \mathbf{x}
- We get the data what should we do?



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Learning bias

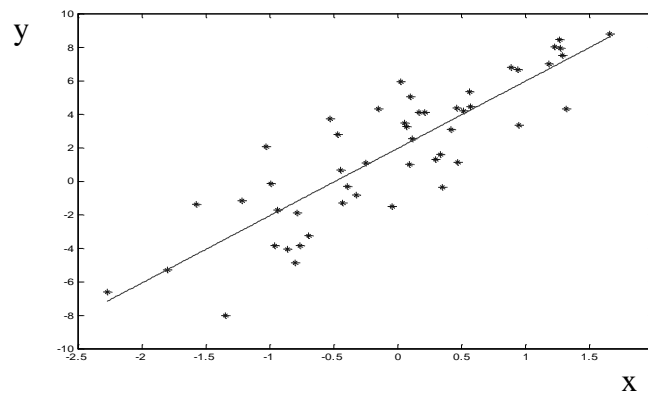
- **Problem:** many possible functions $f : X \rightarrow Y$ exists for representing the mapping between x and y
- Which one to choose? Many samples still unseen!



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Learning bias

- Problem is easier when we make an assumption about the model, say, $f(x) = ax + b + \varepsilon$
 $\varepsilon = N(0, \sigma)$ - random (normally distributed) noise
- Restriction to the linear model is an example of learning bias



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