

# SENSE IN ORDER: CHANNEL SELECTION FOR SENSING IN COGNITIVE RADIO NETWORKS

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# MOTIVATION

## INTRODUCTION

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## CONCLUSION

- Spectrum sensing is one of the key phases in Cognitive radio networks (CRNs).

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- Before data transmission happens, each node (secondary user) needs to find one available channel.

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- Spectrum sensing is one of the key phases in Cognitive radio networks (CRNs).
- Before data transmission happens, each node (secondary user) needs to find one available channel.
- If the channel is unavailable, it needs to adjust its parameters and switch to sense another channel.

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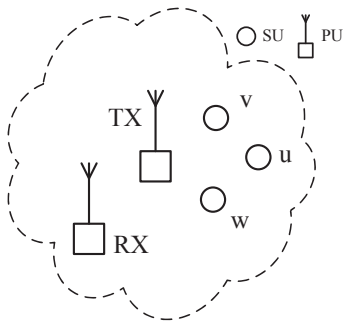
An example:

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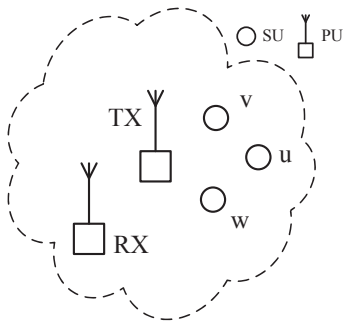
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An example:



An example:



**Q:** How to increase the efficiency for spectrum sensing?

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- Before spectrum sensing, choose the channel that is more likely to be available for sensing.



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- This is practical with the help of nodes nearby.

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- Before spectrum sensing, choose the channel that is more likely to be available for sensing.
- This is practical with the help of nodes nearby.
  - For example, in previous figure, node  $u$  is likely to know which channels are more likely to be available by overhearing some information provided by  $v$  and  $w$ .

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- How to choose a channel for sensing for each node at the beginning:

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- How to choose a channel for sensing for each node at the beginning:
  - “Pre-phase” of spectrum sensing: it happens before the spectrum sensing

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  - The order is determined before the spectrum sensing, and is maintained as a list by each node.

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  - The order is determined before the spectrum sensing, and is maintained as a list by each node.
- Each looks up the list and selects a channel for sensing.

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  - “Pre-phase” of spectrum sensing: it happens before the spectrum sensing
- We propose a sense-in-order (SIO) model for the pre-phase problem:
  - The order is determined before the spectrum sensing, and is maintained as a list by each node.
- Each looks up the list and selects a channel for sensing.
  - Each node knows the order to sense, which results in a reduction of switches among channels during spectrum sensing.



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- A channel is sensed as available if and only if it is neither occupied by primary users nor secondary users.

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- A channel is sensed as available if and only if it is neither occupied by primary users nor secondary users.
- We define the cost  $C_v$  of each node  $v$  during the spectrum sensing as the number of switches among channels that are needed until an available one is found.

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- We define the cost  $C_v$  of each node  $v$  during the spectrum sensing as the number of switches among channels that are needed until an available one is found.
- **Objective:** Provide an order of channels for sensing so that the cost during the spectrum sensing phase is minimized:  $\text{Min } \sum_{v \in N} C_v$ .

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- Each node senses the channel when it needs a channel for transmission, and broadcasts the sensing results through common control channel.

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- If the node finds an available channel, it will access that channel.

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- Each node senses the channel when it needs a channel for transmission, and broadcasts the sensing results through common control channel.
- If the node finds an available channel, it will access that channel.
- The node will also broadcast when it accesses and when it quits that channel.

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The broadcast information can be implemented using the following three signals:

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The broadcast information can be implemented using the following three signals:

- $PO_m$ : channel  $m$  is occupied by primary users;



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The broadcast information can be implemented using the following three signals:

- $PO_m$ : channel  $m$  is occupied by primary users;
- $SO_m$ : channel  $m$  is free from primary users, but is occupied by the secondary user who sent this signal;

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The broadcast information can be implemented using the following three signals:

- $PO_m$ : channel  $m$  is occupied by primary users;
- $SO_m$ : channel  $m$  is free from primary users, but is occupied by the secondary user who sent this signal;
- $SF_m$ : Secondary user finishes transmission and quit from channel  $m$ .

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- Based on the received signals, a node  $v$  is able to identify four different states,  $S = \{S_i, 1 \leq i \leq 4\}$ , for a channel  $m$ .

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- We use  $\langle S_i, m \rangle$  to indicate that channel  $m$  is in state  $S_i$ :

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- We use  $\langle S_i, m \rangle$  to indicate that channel  $m$  is in state  $S_i$ :
  - $\langle S_1, m \rangle$ :  $m$  is occupied by primary users;
  - $\langle S_2, m \rangle$ :  $m$  is not occupied by primary users, but is occupied by the secondary user;
  - $\langle S_3, m \rangle$ : the secondary user previously using  $m$  has finished transmission and quit from  $m$ ;
  - $\langle S_4, m \rangle$ : no signal is received about  $m$ .

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- The four states are maintained on each node itself.

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- The four states are maintained on each node itself.
- For  $\langle S_1, m \rangle$ , node  $v$  is not sure about whether the primary users have finished transmission on  $m$  if no other sensing results are received from other nodes.

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- For  $\langle S_2, m \rangle$ , node  $v$  should avoid sensing  $m$  until  $v$  receives the signal  $SF_m$ .



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- For  $\langle S_3, m \rangle$ , node  $v$  should assign higher probabilities for selecting  $m$  to sense.

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- For  $\langle S_3, m \rangle$ , node  $v$  should assign higher probabilities for selecting  $m$  to sense.
- For  $\langle S_4, m \rangle$ ,  $v$  is not sure about the availability of  $m$  either.

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- Each node changes among the four states based on the signal it receives.

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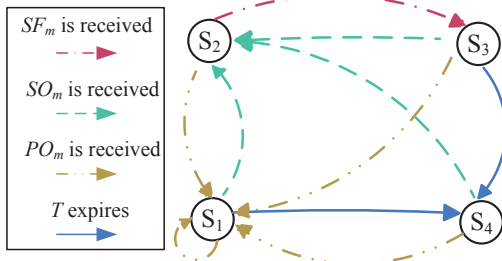
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- How does each node define preferences on different channels:

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- How does each node define preferences on different channels:
- Each node divides the whole channel set into four (at most) different subsets, based on the state of each channel.

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- How does each node define preferences on different channels:
- Each node divides the whole channel set into four (at most) different subsets, based on the state of each channel.
  - For node  $v$ , the whole channel set  $M$  is divided into four subsets  $M_v(S_i)$ ,  $1 \leq i \leq 4$ .
  - If channel  $m \in M_v(S_i)$ , channel  $m$  is identified as state  $S_i$  by node  $v$ .

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  - If channel  $m \in M_v(S_i)$ , channel  $m$  is identified as state  $S_i$  by node  $v$ .
- The probability of each channel to be chosen for sensing is:

$$p_v^m = \begin{cases} \frac{t_m}{\sum_{m_0 \in M_v(S_1)} t_{m_0}} \times P_v(S_1) & m \in M_v(S_1) \\ 0 & m \in M_v(S_2) \\ \frac{T-t_m}{\sum_{m_0 \in M_v(S_3)} (T-t_{m_0})} \times P_v(S_3) & m \in M_v(S_3) \\ \frac{P_v(S_4)}{|M_v(S_4)|} & m \in M_v(S_4) \end{cases} .$$



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The overall structure of our algorithm for a node  $v$  is:

- $v$  updates the state of each channel based on the received signal;

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- $v$  updates the state of each channel based on the received signal;
- When  $v$  needs to transmit data, it calculates the probability of each channel to be chosen and selects one channel to sense until it finds an available one;
- $v$  shares its sensing results with others and sends out the corresponding signal when it accesses and quits that channel.

## SIMULATION RESULTS

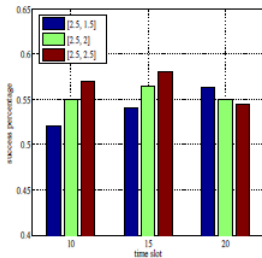
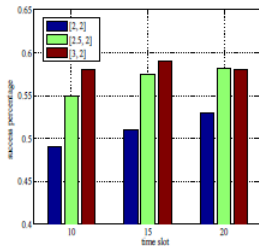
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We evaluate our algorithm performance by varying different parameters, including both network parameters and algorithm parameters.

(a) change  $W_4/W_1$ (b) change  $W_3/W_4$

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- We consider the pre-phase of spectrum sensing, which focus on how to choose a channel for sensing for each node in cognitive radio networks (CRNs).
- We propose an SIO model, which constructs a state transition diagram and a corresponding algorithm for each node to calculate the probability of each channel being chosen for sensing.
- Extensive simulation results testify the efficiency of our model.

*Thank you!*